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## **Optris Ethernet TCP/IP / Modbus TCP communication interface for Optris CT, CTlaser and CTratio**

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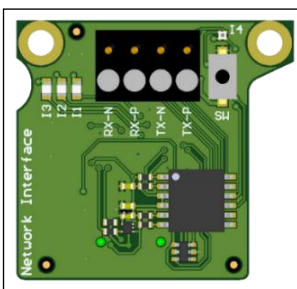
## 1. General

The Optris Ethernet TCP/IP / Modbus TCP interface board can be easily installed inside the electronic box of any CT, CTlaser or CTratio. The interface connector is a 4-pin M12 connector, D-coded, installed on the left side of the CT electronic box. It is suited for industrial communication with an IP67 protection rate and a screw retention feature.

The network settings are stored on the board and the board communicates with the Optris CT via serial interface. The network settings remain on the board in case of interchanging the Optris CT electronic box.

## 2. Scope

The Optris Ethernet TCP/IP / Modbus TCP communication Interface allows you to communicate with your CT via the TCP/IP or Modbus TCP protocol in a network.



For the communication four different possibilities are supplied:

- Compact Connect or CompactPlus Connect – software communication tool for Optris pyrometers.
- Fully developed C# scripts as pre-installed examples as window batch files
- Excel sheet with macros for the TCP/IP communication
- Communication with your Modbus tool via the Modbus TCP protocol

Figure 1: Optris Ethernet TCP/IP / Modbus TCP communication interface board

## 3. Installation overview

Insert the Ethernet TCP/IP / Modbus TCP communication interface board in the CT electronic board like described in ACCTENMBTCPK-MAD-E2024-01-A.pdf. Power the CT electronic box with 8-36 V, the Ethernet TCP/IP / Modbus TCP communication interface board gets the power from the CT electronic box. Connect the Ethernet TCP/IP / Modbus TCP communication interface board socket with a network cable to a switch in your network (**DHCP mode**) – recommended, or directly to your PC (**direct mode**).

The baud rate must be set to 115k baud for the communication between the Optris CT electronic box and the Ethernet TCP/IP / Modbus TCP communication interface board.

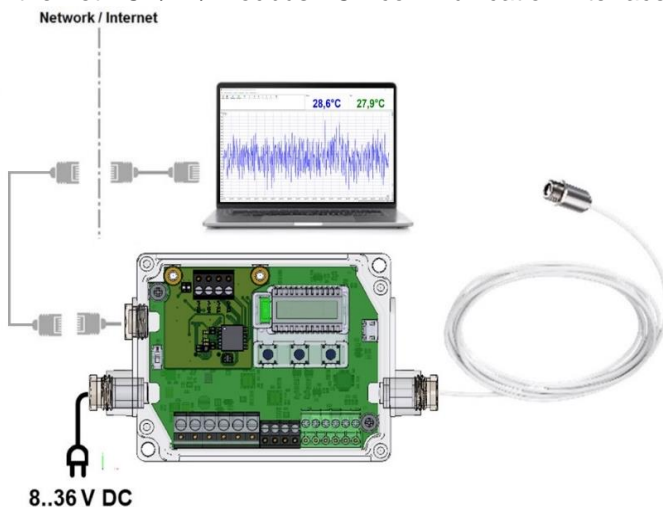


Figure 2: Installation overview

## 3.1 DHCP mode

The Network CT-TCP/IP interface is in DHCP mode by default. Connect the interface to your company network. To find the IP address of the CT-TCP/IP module, use the supplied Excel sheet (3.1.1), the Optris communication software Compact Connect or CompactPlus Connect (3.1.2) or your own DHCP commissioning tool.

### 3.1.1 Supplied Excel sheet

Open the supplied Excel sheet. Under the tab *Discover* click on the button **Discover devices**. All connected CT-TCP/IP modules in your network will be shown in the table. Use the found IP address to communicate with the CT-TCP/IP module.

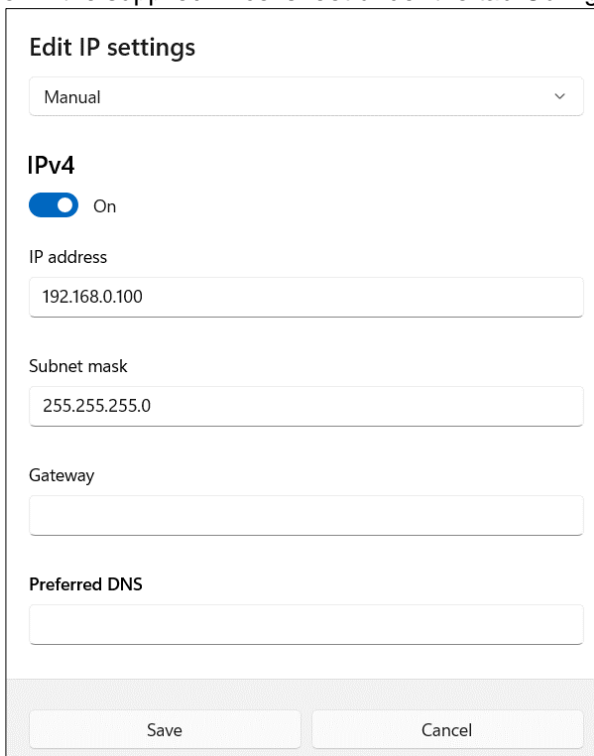
### 3.1.2 Compact Connect or CompactPlus Connect

All connected CT-TCP/IP interfaces in the same subnet will be shown in the software with its IP addresses and serial numbers.

Use the provided C#-Examples to communicate with the Ethernet TCP/IP / Modbus TCP communication interface. Change in the batch files the IP addresses and execute the **Discovery.bat** or **GetConfig.exe** to see your configuration and IP settings and use **the Command.exe** to see the temperatures.

## 3.2 Direct mode

Your Ethernet TCP/IP / Modbus TCP communication interface needs to work in static IP mode. For this purpose, change your settings on your PC to a static IP address. This can be done via the internet browser or in the supplied Excel sheet under the tab *Configuration*.



The image shows a screenshot of the Windows 'Edit IP settings' dialog box. The 'IP assignment method' is set to 'Manual'. The 'IPv4' toggle is turned 'On'. The 'IP address' field contains '192.168.0.100', the 'Subnet mask' field contains '255.255.255.0', and the 'Gateway' and 'Preferred DNS' fields are empty. At the bottom, there are 'Save' and 'Cancel' buttons.

Figure 3: Network settings

The Ethernet TCP/IP / Modbus TCP communication interface is in DHCP mode by default, this needs to be changed to static mode, we recommend to use the web interface or the supplied Excel sheet.

Connect the Ethernet TCP/IP / Modbus TCP communication interface to your PC. Use any DHCP commissioning tool to set the IP address of the Ethernet TCP/IP / Modbus TCP communication interface or use the web interface with the founded IP address of the DHCP mode. Change the DHCP mode of the module to a static IP address with the same subnet and same subnet mask via the web browser or the supplied Excel sheet.

In this picture you see the webpage of the Ethernet TCP/IP / Modbus TCP communication interface.

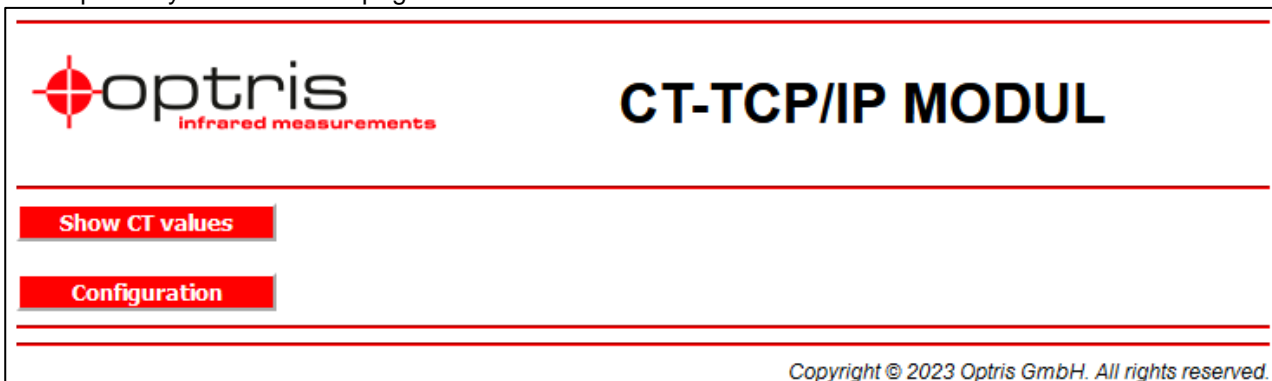


Figure 4: Web interface of the Network CT-TCP/IP Module

Click on **Configuration**. Change the IP address mode to **Static IP** and set the IP address to the network IP address of your computer and click on **Update Settings**.

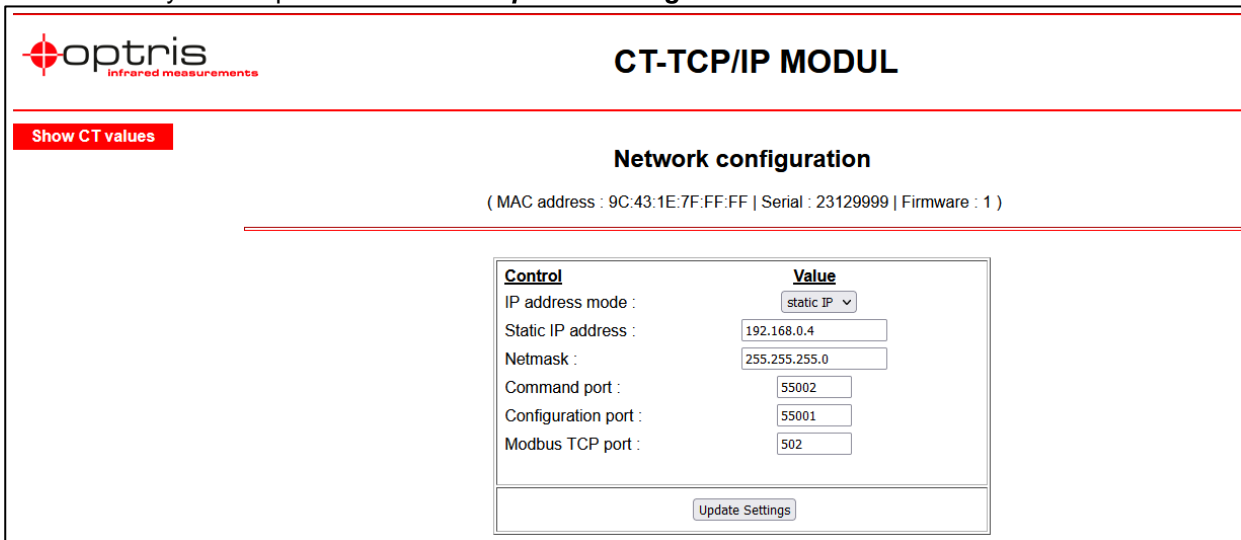


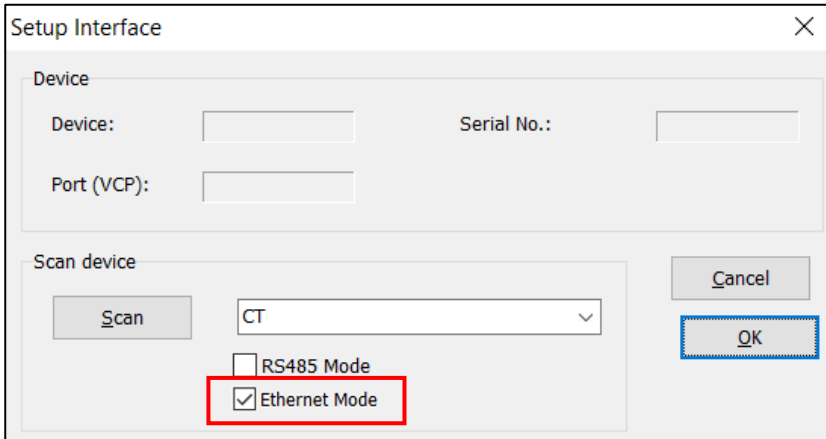
Figure 5: Network Configurations of the CT-TCP/IP module

To change the IP address in the supplied Excel sheet, go to the tab *Configuration* and change the settings for the IP-mode and the static IP address.

## 4. Communication

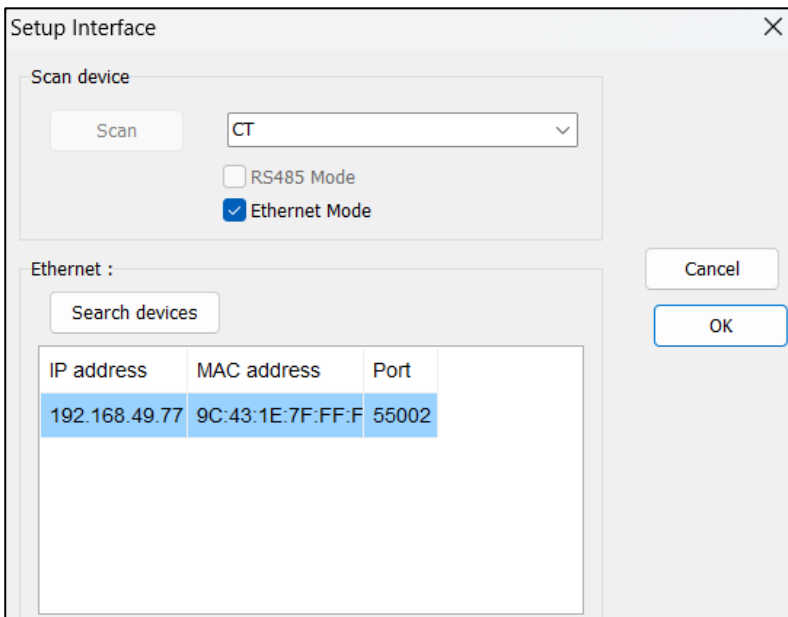
### 4.1 Communication with CompactConnect

Start the supplied software *CompactConnect*. Go to **interface** and set the hook in **Scan device** under **Ethernet Mode**.



**Figure 6:** Setup interface CompactConnect

Click on Search Devices (**Figure 7**). After the *CompactConnect* has found your device click on **OK** and the measurement begins.

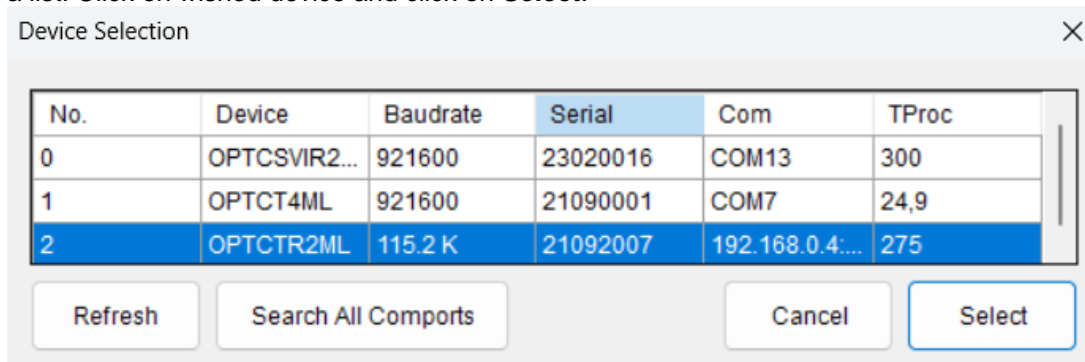


**Figure 7:** Search devices

Note: the earliest version of *CompactConnect* which supports the TCP/IP communication is **1.10.10.2**.

## 4.2 Communication with CompactPlus Connect

Start the software *CompactPlus Connect* and go to **Device** and **Scan Devices**. All devices are shown in a list. Click on wished device and click on **Select**.



Note: the earliest version of *CompactPlus Connect* which supports the TCP/IP communication is **1.6.27**

## 4.3 Communication with Excel

In the supplied Excel sheet, you can find three tabs *Discover*, *Read\_Temp* and *Configuration*. Click on the button **Discover devices** under the *Discover* tab to find all your Ethernet TCP/IP / Modbus TCP communication interfaces with the right IP address in your network. The founded interfaces will be listed in the table TCP/IP devices.

| TCP/IP devices : |                   |        |            |               |             |              |             |
|------------------|-------------------|--------|------------|---------------|-------------|--------------|-------------|
| IP address       | MAC address       | Ipmode | static IP  | subnet mask   | Port config | Port command | Port Modbus |
| 192.168.49.77    | 00:1A:B6:00:02:74 | 0      | 10.10.10.1 | 255.255.255.0 | 55001       | 55002        | 502         |

Under the tab *Read\_Temp* use the drop-down menu button to select founded IP addresses of the CT-TCP/IP modules and click on the button **Connect**, the table will be filled, and the diagram will show the measured temperature values. The table is limited to the set number of values.

In the tab *Configuration* you can change your IP settings for the interface.

## 4.4 Communication with programmed C#-script

A folder with pre-installed files written in C# you can find on the USB flash drive as an example. There are three windows batch files to demonstrate the possibilities of integration into your own software. To communicate with the TCP/IP interface, change in the batch files the IP address to the IP address of the interface and execute the batch files. *Discovery.bat* and *GetConfig.bat* are files to see your configurations and ports. For the temperatures, execute the *command.bat* file.

## 5. LED functions and reset Button

The CT TCP/IP module has 4 LED (I1...I4).

I1 – LED on → The connection to the CT is established

I2 – LED → no function

I3 – LED on → Ethernet connection is established

I3 – LED is flashing → data transfer

I4 – LED → reset function

### 5.1 How to reset the CT communication interface

The CT must be switched off. Press the button **SW** on the board and switch the box on in the meantime. The I4 – LED flashes red. Release the button the fifth time it flashes. I4 – LED flashes green 5 times as confirmation. After reset follow settings are restored:

|                          |                      |
|--------------------------|----------------------|
| <b>IP-Mode:</b>          | <b>DHCP</b>          |
| <b>Static IP:</b>        | <b>192.168.0.1</b>   |
| <b>Subnet mask:</b>      | <b>255.255.255.0</b> |
| <b>Port Modbus:</b>      | <b>502</b>           |
| <b>Port Config data:</b> | <b>55001</b>         |
| <b>Port direkt CT:</b>   | <b>55002</b>         |

## 6. Connection of multiple devices

Each of the devices must get an own IP address but they must be in the same subnet.

## 7. Troubleshooting

In case of missing .NET packages please go to the website <https://dotnet.microsoft.com/en-us/download/dotnet/thank-you/runtime-6.0.25-windows-x64-installer> and download the package for your operating system.

In case of a possibility to communicate directly via the IP address but the CompactConnect software cannot find the TCP/IP module in the network, check the subnet mask, they must be the same.

You can set the module to its default settings if required. Press the button of the module while the CT is not powered. Connect the device to the power supply while holding the button for 5 seconds, the red LED flashes 5 times. Release the button, the green LED I4 turns shortly on.

## 8. Modbus Register list

For the communication with a PLC, you can use a Modbus tool.

Use a Modbus tool with following settings.

Read out the data is done via the **Read Holding Register** and **Read Input Register**.

Changing the settings of the device is done over the **Write Holding Register**.

|                  |               |
|------------------|---------------|
| Connection type: | Tcp           |
| Host address:    | 192.168.49.77 |
| Port:            | 502           |
| Byte order:      | 4321          |

|                            |
|----------------------------|
| 03 Read Holding Registers  |
| 01 Read Coils              |
| 02 Read Discrete Inputs    |
| 03 Read Holding Registers  |
| 04 Read Input Registers    |
| 05 Write Single Coil       |
| 06 Write Single Register   |
| 08 Diagnostics             |
| 15 Write Multiple Coils    |
| 16 Write Holding Registers |

### 8.1 Input Register

| Description           | Type               | Register Address | Register-Size | Data-Format                             | Comment         |
|-----------------------|--------------------|------------------|---------------|---|-----------------|
| Modbus CT FW Revision | R - Input Register | 1000             | 1             | = Value/100                             | Set by Firmware |
| Error-FileID          | R - Input Register | 1001             | 1             | FileID where error is triggered         |                 |
| Error-Line            | R - Input Register | 1002             | 1             | Line in file where error is triggered   |                 |
| Error-Code            | R - Input Register | 1003             | 1             | Error code e.g. HAL_ERROR               |                 |
| Error-Data            | R - Input Register | 1004             | 1             | Additional data e.g. state              |                 |
| Error-Count           | R - Input Register | 1005             | 1             | Count how often this error has occurred |                 |

| Description           | Type               | Register Address | Register-Size | Data-Format   | Comment             |
|-----------------------|--------------------|------------------|---------------|---|---------------------|
| Serial number         | R - Input Register | 1010             | 2             | = Value1*2^16 + Value2  | For CTLT and CTxM   |
| Serial number         | R - Input Register | 1010             | 2             | = Value1*2^16 + Value2  | For CRatio and CT4M |
| CT FW Revision        | R - Input Register | 1012             | 1             | = Value   |                     |
| CT Sensor Information | R - Input Register | 1013             | 3             | Value 1 = Sensor type<br>Value 2 = Lower Temperature<br>Value 3 = Upper Temperature | For CTLT            |

| Description     | Type               | Register Address | Register-Size | Unit | Data-Format           | Comment             |
|-----------------|--------------------|------------------|---------------|------|-----------------------|---------------------|
| Temp. - process | R - Input Register | 1020             | 1             | °C   | = (Value - 1000) / 10 |                     |
| Temp. - Head    | R - Input Register | 1021             | 1             | °C   | = (Value - 1000) / 10 |                     |
| Temp. - Box     | R - Input Register | 1022             | 1             | °C   | = (Value - 1000) / 10 |                     |
| Temp. - Act     | R - Input Register | 1023             | 1             | °C   | = (Value - 1000) / 10 |                     |
| Temp. - Avg     | R - Input Register | 1024             | 1             | °C   | = (Value - 1000) / 10 | For CRatio and CT4M |



|                    |                    |      |   |    |                       |                  |
|--------------------|--------------------|------|---|----|-----------------------|------------------|
| Temp - Ratio       | R - Input Register | 1025 | 1 | °C | = (Value - 1000) / 10 | Only for CTratio |
| Temp - T2          | R - Input Register | 1026 | 1 | °C | = (Value - 1000) / 10 | Only for CTratio |
| Temp - T1          | R - Input Register | 1027 | 1 | °C | = (Value - 1000) / 10 | Only for CTratio |
| Temp - Attenuation | R - Input Register | 1028 | 1 | °C | = (Value - 1000) / 10 | Only for CTratio |

| Description      | Type               | Register Address | Register-Size | Unit<br>[ ] | Data-Format      | Comment              |
|------------------|--------------------|------------------|---------------|-------------|------------------|----------------------|
| Epsilon Act      | R - Input Register | 1040             | 1             |             | = (Value) / 1000 | For CTratio and CT4M |
| Transmission Act | R - Input Register | 1041             | 1             |             | = (Value) / 1000 | For CTratio and CT4M |
| Epsilon T1       | R - Input Register | 1042             | 1             |             | = (Value) / 1000 | Only for CTratio     |
| Epsilon T2       | R - Input Register | 1043             | 1             |             | = (Value) / 1000 | Only for CTratio     |
| Slope            | R - Input Register | 1044             | 1             |             | = (Value) / 1000 | Only for CTratio     |

| Description  | Type               | Register Address | Register-Size | Unit<br>[ ] | Data-Format           | Comment              |
|--------------|--------------------|------------------|---------------|-------------|-----------------------|----------------------|
| F1 mV value  | R - Input Register | 1050             | 1             | mV          | = (Value - 1000) / 10 | For CTratio and CT4M |
| F2 mV value  | R - Input Register | 1051             | 1             | mV          | = (Value - 1000) / 10 | For CTratio and CT4M |
| F3 mV value  | R - Input Register | 1052             | 1             | mV          | = (Value - 1000) / 10 | For CTratio and CT4M |
| IO1 mV value | R - Input Register | 1050             | 1             | mV          | = (Value - 1000) / 10 | For CTratio and CT4M |
| IO2 mV value | R - Input Register | 1051             | 1             | mV          | = (Value - 1000) / 10 | For CTratio and CT4M |
| IO3 mV value | R - Input Register | 1052             | 1             | mV          | = (Value - 1000) / 10 | For CTratio and CT4M |

| Description               | Type               | Register Address | Register-Size | Data-Format | Comment                   |
|---------------------------|--------------------|------------------|---------------|-------------|---------------------------|
| Model Information Block 1 | R - Input Register | 1060             | 15            | Siehe pdf   | Only for CTratio and CT4M |
| Model Information Block 2 | R - Input Register | 1075             | 12            | Siehe pdf   | Only for CTratio and CT4M |

## 8.2 Holding Register

| Description       | Type                   | Register Address | Register-Size | Data-Format                   | Comment                                |
|-------------------|------------------------|------------------|---------------|-------------------------------|--|
| MODBUS-ID         | R/W - Holding Register | 10000            | 1             | ID: 1 - 247                   | MODBUS Setting                         |
| MODBUS Baudrate   | R/W - Holding Register | 10001            | 1             | 1: 9600 Baud<br>2: 19200 Baud | MODBUS Setting                         |
| Error-Count Reset | R/W - Holding Register | 10002            | 1             | 0: Idle 1: Reset              | Resets the error repetition count to 0 |

| Description              | Type                   | Register Address | Register-Size | Unit [ ] | Data-Format   | Comment                   |
|--------------------------|------------------------|------------------|---------------|----------|---|---------------------------|
| Transmission 2           | R/W - Holding Register | 10008            | 1             |          | = (Value) / 1000  | Only for CTratio          |
| Epsilon Slope            | R/W - Holding Register | 10009            | 1             |          | = (Value) / 1000  | Only for CTratio          |
| Epsilon                  | R/W - Holding Register | 10010            | 1             |          | = (Value) / 1000  |                           |
| Transmission             | R/W - Holding Register | 10011            | 1             |          | = (Value) / 1000  |                           |
| Spot Illumination Laser  | R/W - Holding Register | 10012            | 1             |          | 1 = On<br>0 = Off   |                           |
| AVG Time                 | R/W - Holding Register | 10013            | 1             | ms       | = Value   |                           |
| AVG Mode                 | R/W - Holding Register | 10014            | 1             |          | 1 = Smart Averaging<br>0 = Normal                                     |                           |
| Peak Hold Time           | R/W - Holding Register | 10015            | 1             | ms       | = Value   | Only CTLT                 |
| Smart Threshold          | R/W - Holding Register | 10015            | 1             | ms       | = Value   | Only for CTratio and CT4M |
| Valley Hold Time         | R/W - Holding Register | 10016            | 1             | ms       | = Value   | Only CTLT                 |
| Hold time                | R/W - Holding Register | 10016            | 1             | ms       | = Value   | Only for CTratio and CT4M |
| Advanced Hold Mode       | R/W - Holding Register | 10017            | 1             |          | 0 = Off<br>1 = Peak<br>2 = Valley                                     | Only CTLT                 |
| Advanced Hold Mode       | R/W - Holding Register | 10017            | 1             |          | 0 = Off<br>1 = Peak<br>2 = Valley<br>3 = Adv. Peak<br>4 = Adv. Valley | Only for CTratio and CT4M |
| Advanced Hold Threshold  | R/W - Holding Register | 10018            | 1             |          | = (Value - 1000) / 10   |                           |
| Advanced Hold Hysteresis | R/W - Holding Register | 10019            | 1             | °C       | = (Value) / 10  |                           |
| Pick Mode                | R/W - Holding Register | 10020            | 1             | -        | 0 = Off<br>1 = Peak Pick<br>2 = Valley Pick                           | Only for CTLT             |
| ALARMx Mode              | R/W - Holding Register | 10021            | 1             | -        | See CT-CTlaser-CTvideo-commands.pdf                                   | Only for CTLT             |
| Low End for outputs      | R/W - Holding Register | 10022            | 1             | °C       | = (Value - 1000) / 10   | Only for CTLT             |
| High End for outputs     | R/W - Holding Register | 10023            | 1             | °C       | = (Value - 1000) / 10   | Only for CTLT             |
| Skal_Out_Min             | R/W - Holding Register | 10024            | 1             |          | mV or µA  | Only for CTLT             |
| Skal_Out_Max             | R/W - Holding Register | 10025            | 1             |          | mV or µA  | Only for CTLT             |

|  |                        |       |   |    |  |               |
|--|------------------------|-------|---|----|--|---------------|
| AL1 value                                | R/W - Holding Register | 10026 | 1 | °C | = (Value - 1000) / 10                        | Only for CTLT |
| AL2 value                                | R/W - Holding Register | 10027 | 1 | °C | = (Value - 1000) / 10                        | Only for CTLT |
| AL3 value                                | R/W - Holding Register | 10028 | 1 | °C | = (Value - 1000) / 10                        | Only for CTLT |
| AL4 value                                | R/W - Holding Register | 10029 | 1 | °C | = (Value - 1000) / 10                        | Only for CTLT |
| Head Code Block 1                        | R/W - Holding Register | 10030 | 2 |    | see CT-Ctlaser-Ctvideo-commands.pdf, p. 9    | Only for CTLT |
| Head Code Block 2                        | R/W - Holding Register | 10032 | 2 |    | see CT-Ctlaser-Ctvideo-commands.pdf, p. 9    | Only for CTLT |
| Head Code Block 3                        | R/W - Holding Register | 10034 | 2 |    | see CT-Ctlaser-Ctvideo-commands.pdf, p. 9    | Only for CTLT |
| Tweak Offset                             | R/W - Holding Register | 10036 | 1 |    | = (Value - 1000) / 10                        | Only for CTLT |
| User Offset Value                        | R/W - Holding Register | 10036 | 1 | °C | = (Value) / 10                               | Only for CT4M |
| Tweak Gain                               | R/W - Holding Register | 10037 | 1 |    | = (1/2 <sup>15</sup> ) * (Value)             | Only for CTLT |
| User Gain Value                          | R/W - Holding Register | 10037 | 1 |    | = (1/2 <sup>15</sup> ) * (Value)             | Only for CT4M |
| Amb. Temp Source                         | R/W - Holding Register | 10038 | 1 |    | 1 = ext. Analog, 2 = ext. FIX, 3 = Head Temp | Only for CTLT |
| Amb. Temp. Fix Value                     | R/W - Holding Register | 10039 | 1 | °C | = (Value - 1000) / 10                        | Only for CTLT |
| Eps. Source                              | R/W - Holding Register | 10040 | 1 |    | 1 = ext. Analog, 2 = ext. FIX, 3 = Head Temp | Only for CTLT |
| READ Out value for IR-DAC percentage     | R/W - Holding Register | 10041 | 1 |    | Change value to send command                 | Only for CTLT |
| IR DAC percentage                        | R/W - Holding Register | 10042 | 1 | %  | = 0... 100 %                                 | Only for CTLT |
| READ Out value for Amb. DAC percentage   | R/W - Holding Register | 10043 | 1 |    | Change value to send command                 | Only for CTLT |
| Set Amb. DAC percentage                  | R/W - Holding Register | 10044 | 1 | %  | = 0... 100 %                                 | Only for CTLT |
| RESET the DAC percentage output          | R/W - Holding Register | 10045 | 1 |    | Change value to send command                 | Only for CTLT |
| SET Emissivity determination target temp | R/W - Holding Register | 10046 | 1 | °C | = (Value - 1000) / 10                        | Only for CTLT |
| SET Emissivity determination actual temp | R/W - Holding Register | 10047 | 1 | °C | = (Value - 1000) / 10                        | Only for CTLT |

|                                     |                        |       |   |   |   |               |
|-------------------------------------|------------------------|-------|---|---|---|---------------|
| SET Emissivity determination status | R/W - Holding Register | 10048 | 1 | - | 1 = On<br>0 = Off   | Only for CTLT |
| IR Failsafe Mode                    | R/W - Holding Register | 10049 | 1 |   | 0 = always HIGH<br>1 = under → HIGH over → LOW<br>2 = always LOW<br>3 = under → LOW over → HIGH | Only for CTLT |
| Amb. Failsafe Mode                  | R/W - Holding Register | 10050 | 1 |   | 0 = always HIGH<br>1 = under → HIGH over → LOW<br>2 = always LOW<br>3 = under → LOW over → HIGH | Only for CTLT |
| SET DEFAULT                         | R/W - Holding Register | 10051 | 1 |   | Change value to send command  |               |
| PANEL LOCK                          | R/W - Holding Register | 10052 | 1 |   | 0 = Keys available<br>1 = Keys locked   |               |
| Temp. Unit                          | R/W - Holding Register | 10053 | 1 |   | 0 = °C<br>1 = °F  |               |
| Save Settings after changing        | R/W - Holding Register | 10054 | 1 |   | 1 = Data not written in flash<br>0 = Data are written in flash                                  | Only for CTLT |

| Description                  | Type                   | Register Address | Register-Size | Unit [ ] | Data-Format                 | Comment          |
|------------------------------|------------------------|------------------|---------------|----------|-----------------------------|------------------|
| User Offset Value Temp Ratio | R/W - Holding Register | 10060            | 1             | °C       | = (Value - 1000) / 10       | Only for CTratio |
| User Offset Value Temp T1    | R/W - Holding Register | 10061            | 1             | °C       | = (Value - 1000) / 10       | Only for CTratio |
| User Offset Value Temp T2    | R/W - Holding Register | 10062            | 1             | °C       | = (Value - 1000) / 10       | Only for CTratio |
| User Gain Value Temp Ratio   | R/W - Holding Register | 10063            | 1             |          | = (Value) / 2 <sup>15</sup> | Only for CTratio |
| User Gain Value Temp T1      | R/W - Holding Register | 10064            | 1             |          | = (Value) / 2 <sup>15</sup> | Only for CTratio |
| User Gain Value Temp T2      | R/W - Holding Register | 10065            | 1             |          | = (Value) / 2 <sup>15</sup> | Only for CTratio |

| Description                        | Type                   | Register Address | Register-Size | Unit [ ] | Data-Format           | Comment                   |
|------------------------------------|------------------------|------------------|---------------|----------|-----------------------|---------------------------|
| Max Attenuation max. Attenuation   | R/W - Holding Register | 10070            | 1             | %        | = (Value - 1000) / 10 | Only for CTratio          |
| Max Attenuation Mode               | R/W - Holding Register | 10071            | 1             |          |                       | Only for CTratio          |
| Max Attenuation fixed TRatio Value | R/W - Holding Register | 10072            | 1             | °C       | = (Value - 1000) / 10 | Only for CTratio          |
| Ambient Temp Amb. Source           | R/W - Holding Register | 10073            | 1             |          |                       | Only for CTratio and CT4M |

|                                     |                              |       |   |    |                       |                              |
|-------------------------------------|------------------------------|-------|---|----|-----------------------|------------------------------|
| Ambient Temp<br>Amb. Temp           | R/W -<br>Holding<br>Register | 10074 | 1 | °C | = (Value - 1000) / 10 | Only for CTratio and<br>CT4M |
| Ambient Temp<br>Amb. Temp at<br>0V  | R/W -<br>Holding<br>Register | 10075 | 1 | °C | = (Value - 1000) / 10 | Only for CTratio             |
| Ambient Temp<br>Amb. Temp at<br>10V | R/W -<br>Holding<br>Register | 10076 | 1 | °C | = (Value - 1000) / 10 | Only for CTratio             |

| Description                       | Type                         | Register<br>Address | Register-<br>Size | Unit [ ] | Data-Format           | Comment                      |
|-----------------------------------|------------------------------|---------------------|-------------------|----------|-----------------------|------------------------------|
| Output 0<br>Mode                  | R/W -<br>Holding<br>Register | 10080               | 1                 |          |                       | Only for CTratio and<br>CT4M |
| Output 1<br>Mode                  | R/W -<br>Holding<br>Register | 10081               | 1                 |          |                       | Only for CTratio and<br>CT4M |
| Output 0<br>Analog Source         | R/W -<br>Holding<br>Register | 10082               | 1                 |          |                       | Only for CTratio and<br>CT4M |
| Output 1<br>Analog Source         | R/W -<br>Holding<br>Register | 10083               | 1                 |          |                       | Only for CTratio and<br>CT4M |
| Output 0<br>Analog mA<br>below    | R/W -<br>Holding<br>Register | 10084               | 1                 | µA       | = Value               | Only for CTratio and<br>CT4M |
| Output 1<br>Analog mA<br>below    | R/W -<br>Holding<br>Register | 10085               | 1                 | µA       | = Value               | Only for CTratio and<br>CT4M |
| Output 0<br>Analog mA<br>above    | R/W -<br>Holding<br>Register | 10086               | 1                 | µA       | = Value               | Only for CTratio and<br>CT4M |
| Output 1<br>Analog mA<br>above    | R/W -<br>Holding<br>Register | 10087               | 1                 | µA       | = Value               | Only for CTratio and<br>CT4M |
| Output 0<br>Analog Range<br>below | R/W -<br>Holding<br>Register | 10088               | 1                 | °C       | = (Value - 1000) / 10 | Only for CTratio and<br>CT4M |
| Output 1<br>Analog Range<br>below | R/W -<br>Holding<br>Register | 10089               | 1                 | °C       | = (Value - 1000) / 10 | Only for CTratio and<br>CT4M |
| Output 0<br>Analog Range<br>above | R/W -<br>Holding<br>Register | 10090               | 1                 | °C       | = (Value - 1000) / 10 | Only for CTratio and<br>CT4M |
| Output 1<br>Analog Range<br>above | R/W -<br>Holding<br>Register | 10091               | 1                 | °C       | = (Value - 1000) / 10 | Only for CTratio and<br>CT4M |
| Output 0<br>Analog mV<br>below    | R/W -<br>Holding<br>Register | 10092               | 1                 | mV       | = Value               | Only for CT4M                |
| Output 1<br>Analog mV<br>below    | R/W -<br>Holding<br>Register | 10093               | 1                 | mV       | = Value               | Only for CT4M                |
| Output 0<br>Analog mV<br>above    | R/W -<br>Holding<br>Register | 10094               | 1                 | mV       | = Value               | Only for CT4M                |
| Output 1<br>Analog mV<br>above    | R/W -<br>Holding<br>Register | 10095               | 1                 | mV       | = Value               | Only for CT4M                |

| Description                  | Type                   | Register Address | Register-Size | Unit [ ] | Data-Format           | Comment                   |
|------------------------------|------------------------|------------------|---------------|----------|-----------------------|---------------------------|
| IO1 Function                 | R/W - Holding Register | 10100            | 1             |          | = Value               | Only for CTratio and CT4M |
| IO2 Function                 | R/W - Holding Register | 10101            | 1             |          | = Value               | Only for CTratio and CT4M |
| IO3 Function                 | R/W - Holding Register | 10102            | 1             |          | = Value               | Only for CTratio and CT4M |
| IO1 Alarm Threshold Source 1 | R/W - Holding Register | 10103            | 1             | °C       | = (Value - 1000) / 10 | Only for CTratio and CT4M |
| IO1 Alarm Source             | R/W - Holding Register | 10104            | 1             |          |                       | Only for CTratio and CT4M |
| IO2 Alarm Source             | R/W - Holding Register | 10105            | 1             |          |                       | Only for CTratio and CT4M |
| IO3 Alarm Source             | R/W - Holding Register | 10106            | 1             |          |                       | Only for CTratio and CT4M |
| Output 0 Alarm Source        | R/W - Holding Register | 10107            | 1             |          | = (Value - 1000) / 10 | Only for CTratio and CT4M |
| Output 1 Alarm Source        | R/W - Holding Register | 10108            | 1             |          |                       | Only for CTratio and CT4M |
| Output 0 Alarm Threshold     | R/W - Holding Register | 10109            | 1             | °C       | = (Value - 1000) / 10 | Only for CTratio and CT4M |
| Output 1 Alarm Threshold     | R/W - Holding Register | 10110            | 1             | °C       | = (Value - 1000) / 10 | Only for CTratio and CT4M |
| Output 0 Alarm Hysteresis    | R/W - Holding Register | 10111            | 1             | °C       | = (Value) / 10        | Only for CTratio and CT4M |
| Output 1 Alarm Hysteresis    | R/W - Holding Register | 10112            | 1             | °C       | = (Value) / 10        | Only for CTratio and CT4M |
| Output 0 Alarm mA - NO Alarm | R/W - Holding Register | 10113            | 1             | µA       | = Value               | Only for CTratio and CT4M |
| Output 1 Alarm mA - NO Alarm | R/W - Holding Register | 10114            | 1             | µA       | = Value               | Only for CTratio and CT4M |
| Output 0 Alarm mA - Alarm    | R/W - Holding Register | 10115            | 1             | µA       | = Value               | Only for CTratio and CT4M |
| Output 1 Alarm mA - Alarm    | R/W - Holding Register | 10116            | 1             | µA       | = Value               | Only for CTratio and CT4M |
| Output 0 Alarm NO NC         | R/W - Holding Register | 10117            | 1             |          | = Value               | Only for CTratio and CT4M |
| Output 1 Alarm NO NC         | R/W - Holding Register | 10118            | 1             |          | = Value               | Only for CTratio and CT4M |
| Output 0 Alarm mV - NO Alarm | R/W - Holding Register | 10119            | 1             | mV       | = Value               | Only for CT4M             |
| Output 1 Alarm mV - NO Alarm | R/W - Holding Register | 10120            | 1             | mV       | = Value               | Only for CT4M             |

|                              |                              |       |   |    |         |               |
|------------------------------|------------------------------|-------|---|----|---------|---------------|
| Output 0 Alarm<br>mV - Alarm | R/W -<br>Holding<br>Register | 10121 | 1 | mV | = Value | Only for CT4M |
| Output 1 Alarm<br>mV - Alarm | R/W -<br>Holding<br>Register | 10122 | 1 | mV | = Value | Only for CT4M |

| Description                   | Type                         | Register<br>Address | Register-<br>Size | Unit [ ] | Data-Format | Comment                      |
|-------------------------------|------------------------------|---------------------|-------------------|----------|-------------|------------------------------|
| DAC<br>percentage<br>output 1 | R/W -<br>Holding<br>Register | 10130               | 1                 | %        | = Value     | Only for CTratio and<br>CT4M |
| DAC<br>percentage<br>output 2 | R/W -<br>Holding<br>Register | 10131               | 1                 | %        | = Value     | Only for CTratio and<br>CT4M |

## 9. Contact information

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