

Jewell ECV eCompass represents the state of the art in magnetic compassing that delivers high accuracy for its small size, low-cost and low power

The ECV eCompass Series provides stable azimuth, pitch, and roll measurements in dynamic conditions. The ECV's sensor suite consists of the following:

- 3-axis angular rate gyros
- o 3-axis accelerometer
- o 3-axis magnetometer
- o 2-axis electrolytic tilt sensor

The advanced capabilities of the ECV are supported by updated eCompass PC software that simplifies engineering verification and integration tasks. The software provides the following functionality:

Monitor and change compass settings Perform magnetic calibration Capture selected measurement data Maintain communication and setting logs



Advantages:

- ✓ Exceptional dynamic performance
- ✓ High accuracy
- ✓ Precise factory calibration
- ✓ Wide Operating range
- ✓ RS232 & RS485 output available
- ✓ Fast response
- ✓ Low power

Rev C

Applications:

- o Unmanned vehicles
- o Robotics
- o Platform stabilization
- Excavation machinery
- And more

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Features:

Static Accuracy

- Azimuth within 0.5° typical (0.1° resolution)
- Pitch and roll within 0.2°

Dynamic Performance

- Gyro gimbal equations performed in firmware
- Azimuth within 3° typical for rates < 150 °/sec
- Pitch and roll within 1° typical for rates < 150 °/sec

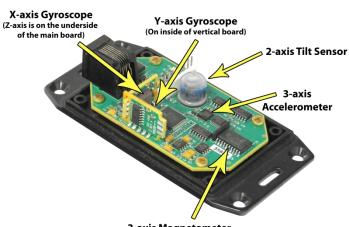
Wide Operating Range

- Ambient temperature -40° to 105°C (-40° to 220°F)
- ±300°/sec angular rate
- Total magnetic field (earth + hard-iron) to \pm 1.5 Gauss
- $\pm 80^{\circ}$ dip angle range
- Total acceleration field to 1.5g (gravity = 1g)
- ±90° electrolytic tilt sensor pitch & roll range (±180° optional)

Fast Response

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- Up to 27.5 calibrated measurements per second
- Wake from standby in 50 msec



3-axis Magnetometer

Single Supply Operation

- 7 to 45V unregulated DC
- Thermal overload and reverse polarity protection

Low Power

- 40 mA operating
- 10 mA idle
- 5 mA standby

Wide Selection of ASCII or Binary Output data

- Heading, pitch, and roll
- Temperature, input voltage, and dip angle
- Magnetometer X, Y, and Z
- Total, horizontal, and vertical magnetic field strength
- Raw and conditioned gyro data

Two independent serial channels

- Full-duplex RS-232 for the external RJ12
- Either RS-232 or full-duplex RS-485 for the internal connector

In-System Configuration and Test

- Laptop can be connected while unit operates in situ
- Perform hard and soft iron calibration
- Monitor outputs and change user-definable settings

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Specifications*:

Heading Performance

Baramatar	Value	Conditions
Parameter	Value	Conditions
Accuracy ¹	$\pm 0.5^{\circ}$ rms	Static, Tilt < 35° Dip < 60°
Accuracy	\pm 3.0° rms	Dynamic, rate < 150°/sec
Repeatability	± 0.3°	Static, no filter
Response time	36 msec	Minimum, no filter
Dip Angle Range	± 80°	
Tilt Range	\pm 90° Pitch/ \pm 180° Roll	
Update rate	27.5 measurements per second	

¹ May require calibration after installation to eliminate effect of local magnetic field

Pitch and Roll Performance

Parameter	Value	Conditions
Accuracy	± 0.3°	Factory calibrated
Repeatability	± 0.2°	No filter
Range	± 90° Pitch/± 180° Roll	(± 42°) electrolytic tilt only
Settling time	50 msec	Gyro enabled

Electrical

Parameter	Value	Conditions
Supply Voltage (V _{DD})	7 - 45Vdc unregulated	
	40 mA operating	
Supply Current	10 mA idle	typical
	05 mA standby	

Environmental

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Parameter	Value	Conditions
Operating Temp	-40° to 105°C	-20°C with electrolytic tilt
Storage Temperature	-50° to 150°C	
Humidity	0 to 90%	Non-condensing
Shock	200g	Max horizontal (with electrolytic tilt)

*Specifications subject to change without notice on account of continued product development

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Specifications (cont'd) *:

Mechanical		
Parameter	Value	
Enclosure material	Plastic Enclosure (P Option): (ABS) Flame Retardant UL94 VO	
Enclosure material	Aluminum Enclosure (A Option): Diecast Aluminum Alloy (Type 360.1)	
PCB Size	1.8"W x 3.0"L x 0.6"H	
PCB Mounting	4 #4 screws, 1.4" x 2.6" spacing	
Connectors	8 pin, single-row, 0.1" friction header	
Connectors	6 pin RJ12 modular jack	
Weight	Plastic Enclosure (P Option): 3.2 oz. (90.7 grams)	
	Aluminum Enclosure (A Option): 7.2 oz. (204.1 grams)	

Interface

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Parameter	Value
Signal type	RS-232 and RS-485
Baud rate	2400, 4800, 9600, 19200, or 38400 bps
Character Format	8 data, no parity, 1 stop
Input Buffer Size	110 characters
Output Buffer Size	110 characters
Output Format	NMEA 0183 and binary
Output Data Rate	1 to 1650 sentences per minute
Operating Modes	Continuous or sample
Angle Units	Degrees, mils, radians, 16-bit integer

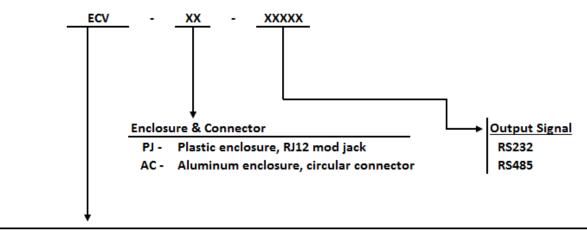
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How to Order:



ECV - Electronic Compass with 3-axis magnetometer, 3-axis gyroscope, 2-axis tilt sensor & 3-axis accelerometer

Example:

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Series

ECV-PJ-RS232

ECV Electronic Compass with 3-axis magnetometer, 3-axis gyroscope, 2-axis tilt sensor & 3-axis accelerometer plastic enclosure, RJ12 mod jack & RS232 output signal

Model & Part numbers:

Model Number	Part Number
ECV-P/J-RS232	02550403-ECV-001
ECV-P/J-RS485	02550403-ECV-004
ECV-A/C-RS232	02550403-ECV-002
ECV-A/C-RS485	02550403-ECV-003

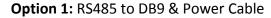


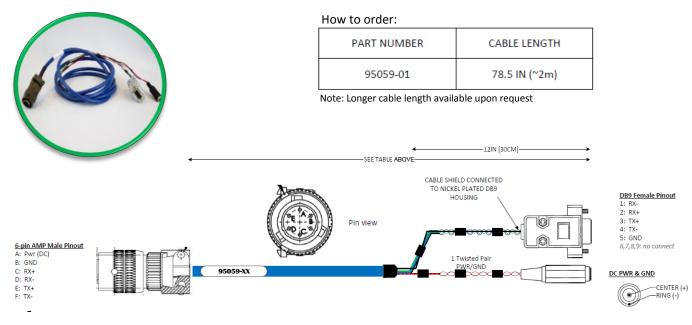
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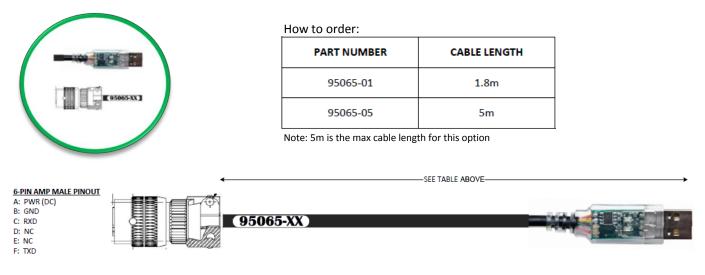
Cable options:





Option 2: RS232 to USB Cable

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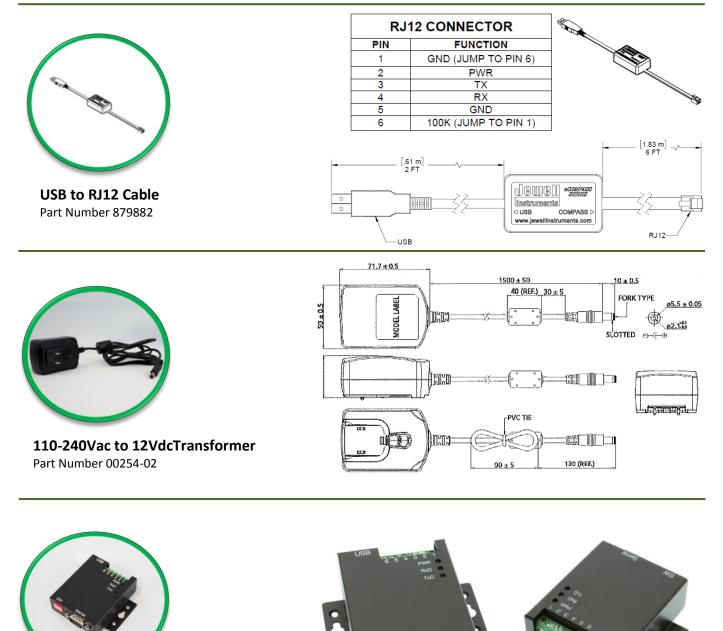
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PIIP

Instruments

Other accessories:



USB to RS232/RS485 Converter Part Number F849284

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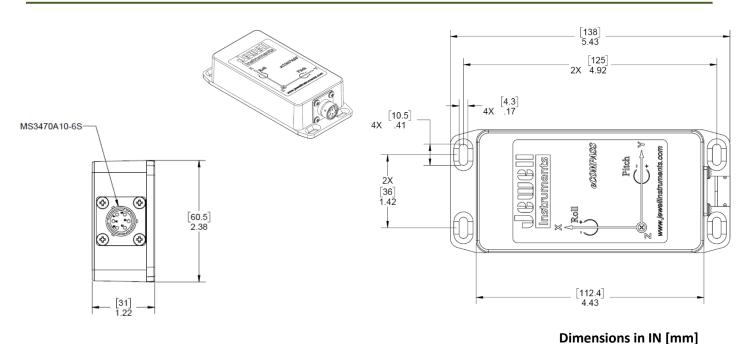
Dimensions: 5 x 4 x 2.5 in

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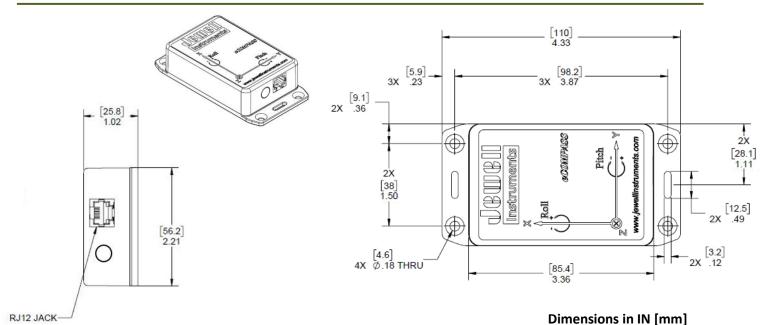


Outline Drawings (Aluminum enclosure):



Outline Drawings (Plastic enclosure):

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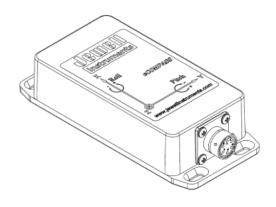
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Pin Out (Aluminum enclosure):

Circular Connector	RS232	RS485
Pin A	Power (7-	-45 Vdc)
Pin B	Grou	und
Pin C	RX	RX+
Pin D	-	RX-
Pin E	10 17	TX+
Pin F	ТХ	TX-



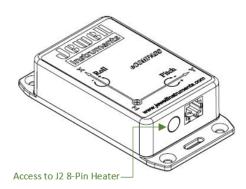
Pin Out (Plastic enclosure):

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RJ12 Mod Jack	Function
Pin 1	GND (Jump to Pin 6)
Pin 2	Power
Pin 3	ТХ
Pin 4	RX
Pin 5	GND
Pin 6	100K (Jump to Pin 1)

J2 8-P	IN Heater (RS485)	Wire
Pin 1	Power	Red
Pin 2	RS232 TX Out	Violet
Pin 3	RS232 RX In	Brown
Pin 4	RS485 RX+	Blue
Pin 5	RS485 RX-	Yellow
Pin 6	Ground	Black
Pin 7	RS485 TX+	Orange
Pin 8	RS485 TX-	Green





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Other Resources:

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