DLR334 PRESSURE INDICATOR

DUPLEX

SERIAL PROTOCOL



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DLR334 PRESSURE DUPLEX SERIAL PROTOCOL

1.0 GENERAL:

- > This document applies to the basic Pressure program KDG-1.
- > The duplex protocol includes the following basic functions:
 - Setup entry and recall.
 - Current pressure data recall.
 - Calibration and correction recall and entry.
 - All front panel key functions.
 - Temperature calibration and correction recall and entry.
- The protocol between the "standard" full duplex and the RS485 will only differ by the addition of the origin and destination address characters.
- > The protocol will be designed to be expandable for future growth and special applications.

2.0 FULL DUPLEX PROTOCOL:

Communications from the host computer into the DLR:

*<DD><OO><cmd><{><data entry><}><CHECK><CR>

Response from the DLR:

:<OO><DD><cmd r><{><data resp><}><CHECK><CR>

Where:

"<",">" Brackets are not sent

*	=	Message from master (host computer)(2AH).
:		Response from DLR (3AH).
DD	=	DLR unit address (two digit) if in RS485.
00	=	Master address (fixed at 00) if in RS485.
		If RS485 mode not selected the "DD" and "OO" are not transmitted.
Cmd	=	Three character command to DLR.
Cmd r	=	Three character command echoed from DLR.
{	=	Start of data character (7BH).
}	=	End of data character (7DH).
		'{' and '}' only sent if data entry or recall.
Data entry	=	Data entered into DLR if entry command.
Data resp	=	Data response from DLR if in response.
CHECK	=	Optional two character check if selected.
CR	=	Message terminator (0DH).
		A "LF" character following the "CR" will be ignored. All characters following

the "CR" and preceding the "*" will be ignored.

3.0 **COMMAND CODE <cmd> DESCRIPTION:**

The <cmd> consists of three (3) characters "ppt" where:

pp = the command parameter.T = the command type.

The three (3) command types (t) are as follows:

Direct cmd code = < D > character (44H). 'D' Commands have no data associated with them.

- General commands (Zero, etc.).
- Display commands (Min,Max, etc.).
- Pressure calibration (Zero Cal, etc.).

Data request code = < R > character (3FH).

- 'R' commands requesting data from the host to the DLR.
 - Pressure data.
 - Status.
 - Setup data.

Calibration data.

Data entry code $= \langle E \rangle$ character (45H).

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- 'E' commands with data sent from host to be entered into the DLR.
 - Setup data.
 - Calibration data.

For complete listing of command codes see Table II.

4.0 **DATA FORMAT:**

4.1 GENERAL:

- > When data is transmitted it is always bracketed with the '{' and '}' characters.
- > The separation character '|' (7CH) is used to separate data in a string.
- > All DLR recalled data has leading zero suppression with the zeros transmitted as spaces.
- All data entered into the DLR can have leading zero suppression with the zeros transmitted as spaces but is not required.
- Summary of data formats:

PRESSURE: <value><units><par><stat> STATUS: WEIGHT: <stat> INPUT: <I1>|<I2> OUTPUT: <O1>|<O2> SETUP: <par 1>|<par 2>| - - - <par x>

5.0 **RESPONSE:**

In the print/port 1/duplex setup the response by the DLR from the direct commands and data entry commands can be selected for 'None' or Echo'.

'None': no response is given a direct cmd (D) or data entry cmd (E) if valid or invalid.

'Echo': the command (direct or entry) is echoed as received if valid; the start of transmission character is returned with a ':' not the '*' character. If invalid a _NAK_ is returned

'**Ack/Nak**': instead of echoing back the received command code and entered data the DLR responds with 'ACK' (41H, 43H & 48H) in place of the code. If an error in received data is detected the DLR responds with 'NAK'(4EH, 41H & 48H).

Ack response: :ACK<CR> Nak response: :NAK<CR>

- > An **invalid** input consists of the following:
 - Parity error.
 - Check error if enabled.
 - Invalid command code.
 - Invalid data format.

Response in Echo or Ack/Nak mode = :NAK<CR>

> Commands received as **valid** but that can **not be performed**:

A valid command in the Echo or Ack/Nak mode that can not be performed will respond with: :NAC<CA>

The conditions that give you a '**NAC**' response are:

- Not in a valid mode for the command. For example, a 'Cal' command in the 'normal (run)' mode (Refer to Command Performance Status Table Below).
- The Command is acting on a parameter that is disabled in Configuration. For example, Peak data recall command when the Peak is configured for 'off'. (Refer to Command Performance Status Table I Below).
- The command is acting on a parameter that can not be performed due to the unit conditions such as motion or over range.

C	OMMAND 'PERFORM' STATUS TA	ABLE I	COMMAND 'PERFORM' STATUS TABLE I						
CATEGORY	COMMANDS	MODE VALID	CONFIG. ENABLED						
GENERAL	ZED, TAD	RUN	YES						
DATA RECALL	PDR, PGR	RUN/CAL	NO						
DATA RECALL	PNR, PWR, PPR, PMR, PVR, PHR	RUN	YES						
STATUS RECALL	PSR, MSR, ISR, OSR	RUN	YES						
DISPLAY SELECT	MGD	RUN/CAL	NO						
DISPLAY SELECT	MND, MPD, MMD	RUN	YES						
UNITS SELECT	UxD	RUN	YES						
UNITS SELECT	UUE/UUR	CAL	NO						
PRINT	PRD	RUN	YES						
CAPACITY/RES	CPE/CPR, REE/RER	CAL	NO						
CALIBRATION	ZRD, RxD, LxE, ZFE/ZFR, LXE/LXR, LFE/LFR, LCE/LCR , HCE, HFE/HFR	CAL	NO						
SETUP	SUE/SUR, FLE/FLR, P2E/P2R, INE/INR, TME/TMR, DTE/DTR, TIE/TIR, PAE/PAR, ANE/ANR, TNE/TNR	CAL	-						
TEMPERATURE CAL	TPD, TXD, TRD, TFR, RZD, RSD, HxD, CxD, TxE/TxR	CAL	NO						

Protocol of responses:

Direct cmd o	code: cmd = *	<pre>cmdD ><cr></cr></pre>	
RESPONSE	VALID ENTRY	INVALID ENTRY CAN	INOT PERFORM
(NONE) =	(NONE)	(NONE)	(NONE)
(ECHO) =	: <cmd d=""><cr></cr></cmd>	:NAK<ČR>	:NAC <cr></cr>
(ACK) =	:ACK <cr></cr>	:NAK <cr></cr>	:NAC <cr></cr>
	RESPONSE (NONE) = (ECHO) =	Direct cmd code:cmd = 'RESPONSEVALID ENTRY(NONE) =(NONE)(ECHO) =: <cmd d=""><cr>(ACK) =:ACK <cr></cr></cr></cmd>	RESPONSEVALID ENTRYINVALID ENTRY CAN(NONE) =(NONE)(NONE)(ECHO) =: <cmd d=""><cr>:NAK<cr></cr></cr></cmd>

Data request code: cmd = *<cmdR><CR>

<u>RESPONSE</u>	<u>VALID ENTRY</u>	INVALID ENTRY	CAN NOT PERFORM
(NONE) =	: <cmdr><{data}><cr></cr></cmdr>	(NONE)	(NONE)
(ECHO) =	: <cmdr><{data}><cr></cr></cmdr>	:NAK <cr></cr>	:NAC <cr></cr>
(ACK) =	: <cmdr><{data}><cr></cr></cmdr>	:NAK <cr></cr>	:NAC <cr></cr>

Data entry code: cmd= *<cmdE><{data}><CR>

<u>RESPONSE</u>	VALID ENTRY	INVALIE	ENTRY	CAN NOT	<u> PERFORM</u>
(NONE) =	(NONE)		(NONE)		(NONE)
(ECHO) =	: <cmde><cr></cr></cmde>		:NAK<ĆF	२>	:NAC <cr></cr>
(ACK) =	:ACK <cr></cr>	:NAK <cr></cr>		:NAC <c< td=""><td>CR></td></c<>	CR>

6.0 **CHECK OPTION:**

The check option is setup in the print duplex mode of port 1. It can be applied to the duplex serial in the RS485 mode or in non addressable mode.

If check setup is set for 'NONE' (OFF), no characters are transmitted for check.

Checksum: if checksum is selected the check consists of two ASCII characters.

- All ASCII characters including the starting character and terminating character preceding the checksum is included in the checksum.
 - The ASCII characters are binary summed (not including the parity bit).
- The least significant byte is divided into four bits each "nibbles" and 30H is added to each. Therefore a sum of 5EH will be transmitted as 35H and 3EH or '5>'.

Xor: if exclusive or is selected the check consists of two ASCII characters.

- All ASCII characters preceding the checksum are exclusively or'ed together.
- The check byte is then calculated to give a result of zero when it is exclusively or'ed in.
- The check byte is divided into four bits each and 30H is added to each.

7.0 **RS485:**

The RS485 protocol is the same as the standard duplex except the two character destination address and two character origin address is included after the starting character.

The host computer's address is fixed at '00' and the DLR address can be set between 1 and 98.

When the setup is not set for the RS485 mode the RS485 transceiver is set for transmit only (RS422 applications).

8.0 **COMMAND CODE SUMMARY:**

The Response is shown in the 'Ack/Nak' mode.

The 'D' column represents the data character length including the '|' seperator but not the '{'or'}' brackets.

COMMAND CODE SUMMARY TABLE II						
COMMAND		RESPONSE	D	DESCRIPTION		
GENERAL:						
ZED	ACK		-	Zero.		
TAD	ACK		-	Tare. ;later		
WEIGHT/PRESSURE/RATE DAT	A RECA	ALL:				
PDR	PDR	{pr,units,par,stat}	11	Display data recall.		
PGR	PGR	{pr,units,par,stat}	11	Pressure recall.		
PVR	PVR	{pr,units,par,stat}	11	R.P.M. recall		
PHR	PHR	{pr,units,par,stat}	11	HP recall		
PNR	PNR	{pr,units,par,stat}	11	ΔT recall. ;later		
PPR	PPR	{pr,units,par,stat}	11	Max data recall.		
PMR	PMR	{pr,units,par,stat}	11	Min data recall.		
STATUS RECALL:						
PSR	PSR	{stat}	1	Pressure status recall (motion, etc.)		
MSR	MSR	{units,mode}	3	Unit/mode status recall.		
ISR	ISR	{I1 I2}	3	Input status recall.		

COMMAND CODE SUMMARY TABLE II							
C	OMMAND	RESPONSE	D	DESCRIPTION			
_	-						
OSR		OSR {01 02}	3	Output status recall. :later			
DISPLAY:		031 {0102}	3				
MPD		ACK	-	Display to Max mode. ;later			
MMD		ACK	-	Display to Min mode. ;later			
		AON	-				
UxD		ACK	-	Conv. Select units (x=A,B,C etc. per			
			-	Table III)			
UUE	{unit1 unit2}	ACK	1	Base 'Cal' units entry.			
UUR		UUR {unit1 unit2}	3	Base 'Cal' units recall.			
PRINT:							
PRD		ACK	-	Print to printer Port 2. ;later			
CAPACITY							
CPE	{cap}	ACK	6	Capacity entry.			
CPR		CPR {cap}	6	Capacity recall.			
REE	{res}	ACK	5	Resolution entry.			
RER		RER {res}	5	Resolution recall.			
CALIBRATI	ON:						
ZCD		ACK	6	Perform zero cal.			
RxD		ACK		Perform linear reset at span x;			
				Where x is a # from 1 – 9 or letter 'a'.			
HCE	{data}	ACK	166	Perform hysteresis correction.			
LxE	{data}	ACK	6	Perform linear cal at point x; Where			
	(00.00)		Ū	x is a # from $1 - 9$ or the letter 'a'			
				(linear on).			
ZFE	{x1 c1}	ACK	17	Zero cal correction entry.			
ZFR		ZFR {x1/c1}	17	Zero cal correction recall.			
LXE	{x1 x9 xA}	ACK	89	Span cal linear corr. All X's entry.			
LXR		LXR {x1 x9 xA}	89	Span cal linear corr. All X's recall.			
LFE	{x1 x9 xA}	ACK	89	Span cal linear corr. All S's entry.			
LFR		LFR {x1 x9 xA}	89	Span cal linear corr. All S's recall.			
LCE	{x1 x9 xA}	ACK	89	Span cal linear corr. All C's entry.			
LCR		LCR {x1 x9 xA}	89	Span cal linear corr. All C's recall.			
HFE	{x1 c1}	ACK	17	Hysteresis (X and C) corr. Entry.			
HFR		HFR {x1 c1}	17	Hysteresis (X and C) corr. Recall.			
SETUP DAT	ſA:						
SUE	{d/s min}	ACK	13				
SUR		SUR {d/s min}	13	Main pressure setup recall.			
FLE	{fil}	ACK		Filter setup entry.			
FLR		FLR {fil}		Filter setup recall.			
NE	{ 1 2}	ACK		Input setup entry.			
INR		INR { 1 2}		Input setup recall.			
P2E	{s1 s7}	ACK		Port 2 serial setup entry.			
P2R		P2R {s1 s7}		Port 2 serial setup recall.			
TME	{hhmm}	ACK		Time entry.			
TMR		TMR {hhmm}		Time recall.			
DTE	{mmddyy}	ACK		Date entry.			
DTR	* * *	DTR {mmddyy}		Date recall.			
TIE	{time/date}	ACK		Time and Date setup entry.			
		1					

COMMAND CODE SUMMARY TABLE II						
COMMAND	RESPONSE	D	DESCRIPTION			
TIR	TIR {time/date}		Time and Date setup recall.			
PAE {p1}	ACK		Parrallel I/O setup entry.			
PAR	PAR {p1}		Parrallel I/O setup recall.			
ANE {anlg 1 sp adj}	ACK		Analog setup entry.			
ANR	ANR { anlg 1 sp adj }		Analog setup recall.			
TNE { }	ACK		Setpoint (Trip point) entry			
TNR	TNR { }		Setpoint (Trip point) recall			
TEMPERATURE CAL:		-				
TPD	ACK	-	Temperature Cal on.			
TXD	ACK	-	Temperature Cal off.			
TRD	ACK	-	Temperature Cal Reset.			
TFR	TFR {t data}	8	Temperature reading (current) recall.			
RZD	ACK	-	Zero Temp Reference acquire.			
RSD	ACK	-	Span Temp Reference acquire.			
HxD	ACK	-	Zero Temp Hot acquire (x-1,2 or 3).			
HxD	ACK	-	Span Temp Hot acquire (x=X,Y or Z).			
CxD	ACK	-	Zero Temp Cold acquire(x=1,2 or 3).			
CxD	ACK	-	Span Temp Cold acquire(x=X,Y or Z).			
DxE {}	ACK		Temp. corrections entry (x=1 or 2).			
DxR	DxR {}		Temp. corrections recall (x=1 or 2).			
TxR	TxR {}		Temp. diag. data recall (x=1,2 or 3).			

9.0 RECALLED DATA:

COMMANDS:

- PDR = Display data.
- = Pressure data = Delta Pressure. PGR
- **PNR**
- PPR = Max data.
- = Min data. PMR

;later

RESPONSE DATA:

DATA FORMAT: LENGTH: WHERE:

<pr><unit1><unit2><par><stat> fixed at 12 characters.

pr: Eight (8) character data field for pressure including polarity and decimal point. Has "space" for positive data and "minus" (-) for negative data.
 Unit1 & 2:Two (2) characters (Refer to Table III and Table IV)

TABLE III					•	TABLE IV
	Pressure 'unit 1' Assignment				Pres	sure 'unit 2'
Unit 1	DESCRIPTION	Unit 1	DESCRIPTION		Unit 2	DESCRIPTION
А	mmHgOEC	K	Кра		А	ABSOLUTE
В	BAR	L	Mbar		G	GAGE

V

С	CmH ₂ O	М	mmH ₂ O4EC
D	inHgOEC	N	PASCAL
E	Kg/cm ²	0	(SPARE)
F	FtseaH ₂ O	Р	PSI
G	inH ₂ O60F	Q	(SPARE)
Н	inH ₂ O68F	R	(SPARE)
I	inH ₂ O4EC	S	(SPARE)
J	MetrsH ₂ O	Т	TORR

one (1) character data field per Table V; par:

	TABLE V						
"	par' ASSIGNMENT						
<par></par>	DESCRIPTION						
'sp'	Standard Pressure						
Ν	Net (pressure with Tare)						
Т	Tare						
Н	нР						
Р	Max						
М	Min						
F	Freeze						

stat:

one (1) character data field;

- = Invalid data U = Under range
 - 0 Μ

'Sp'

- = Over range = Motion
- С = Center of zero
- = None of the above

10.0 STATUS RECALLED:

- > COMMANDS:
 - PSR = Pressure status (motion, etc).

L

- MSR = Unit/mode status
- ISR = Input status.
- OSR = Output status.
- Units/Mode status (MSR command)

DATA FORMAT: <unit1><unit2>|<mode> LENGTH: Fixed at 4 characters.

WHERE:

Unit1&2: Two (2) character field. For character assignment refer to Table III & Table IV.

One (1) character field. For character assignment refer to Table VI. par:

TABLE VI				
'mode' ASSIGNMENT				
<mode></mode>	DESCRIPTION			
N	Standard			
С	Cal/config			

Т	Temp
D	Diagnostic ;later

- \geq Pressure status (PSR command)
- DATA FORMAT: <stat> LENGTH: Fixed at 1 character WHERE: stat: one character data field; Т = invalid data Ο = over range U = under range Μ = motion = center of zero С 'Sp' = none of the above Input status (ISR command): \geq DATA FORMAT: <i1>|<i2> LENGTH: Fixed at 3 characters WHERE: i1 = input 1 status i2 = input 2 status 0 represents an open input (logic 1) 1 represents a closed input (logic 0) = seperation character. \geq Output status (**OSR** command): DATA FORMAT: <01>|<02> LENGTH: Fixed at 3 characters WHERE: **o1** = output 1 status **o2** = output 2 status 0 represents an open output (logic 1) 1 represents a closed output (logic 0)
 - = separation character.

11.0 CAPACITY/RESOLUTION ENTRY AND RECALL:

- COMMANDS: \triangleright CPE{} / CPR = Capacity. = Resolution. REE{} / RER
- Capacity DATA entry (CPE{} command) and recall (CPR command): \geq DATA FORMAT: <data> LENGTH: Fixed at 6 characters. data: Six (6) character data field with no polarity and decimal point. WHERE: -Entry with or without leading zero blanking. -Recall with leading zero blanking.
- Resolution DATA entry (REE{} command) and recall (RER command): \geq DATA FORMAT: <data> LENGTH: Fixed at 5 characters. WHERE: data: Five (5) character data field including decimal point when required. -On Entry and Recall, if a decimal point is included then use full leading zeros; if no decimal point is included then begin data with a space followed by leading zeros.

12.0 **BASE UNITS ENTRY AND RECALL:**

 \triangleright COMMANDS:

= BASE UNITS ENTRY AND RECALL UUE{}/UUR

\triangleright	Cal Units DATA en	try (UUE {} command) and recall (UUR command)
	FORMAT:	<unit1><unit 2=""></unit></unit1>
	LENGTH:	Fixed at two (2) characters.
	WHERE:	
	unit1	: Table III (P=PSI, etc.).
	unit2	: Table IV (G=Gage,etc.).

13.0 **CALIBRATION:**

➤ General:

The unit must be set for Calibration (Mode Rocker switch 1 or 2 closed).

> COMMANDS:

ZCD	= Perform Zero Cal
RxD	= Perform Linear Reset at point x(x is # from 1 - 9 or letter 'A')
LxE{}	= Perform Linear Cal at point x (x is a # from 1 - 9 or the letter 'A').
ZFE{} / ZFR	= Zero Cal correction.
LXE{}/LXR	= Span Cal linear corr. All X's.
LFE{}/LFR	= Span Cal linear corr. All S's.
LCE{}/LCR	= Span Cal linear corr. All C's.
HCE{}	= Perform Hysteresis cal.
HFE{} / HFR	= Hysteresis correction.
	·

> Calibration 'Perform' command data entry:

COMMANDS: LxE{},	, HCE{}
DATA FORMAT:	<data></data>
LENGTH:	Fixed at 6 characters.
WHERE:	data: Six (6) character data field with leading zeros and no
	decimal point.
EXAMPLE:	10.00 PSI entered as {001000}

> Calibration 'Correction' command data entry and recall:

- Zero Cal and Hysteresis correction data; COMMANDS: ZFE{}/ZFR, HFE{}/HFR DATA FORMAT: <x1>|<c1> LENGTH: Fixed at 17 characters. WHERE: x1, c1 = Eight (8) character data fields
- Span Cal Linear corrections (all X's,S's, C's) commands entry and recall data: COMMANDS: LXE{}/LXR, LFE{}/LFR, LCE{}/LCR DATA FORMAT: <x1><|><x2><|><x3><|><x4><|><x5><|><x6><|><x7><|> <x8><|><x9><|><xA>
 LENGTH: Fixed at 89characters. WHERE: x1 - xA: Eight (8) character data field each.

14.0 **SETUP DATA:**

- 14.1 **GENERAL**:
 - ♦ FORMAT: <par 1>|<par 2>| - <par x>
 - Setup data is set in a string using the separation character '|' between parameters.
 - The parameters are listed in the order of the function diagram as they appear in the manual.
 - 'Arrow' select parameters are represented as a number starting with '0'.
 - Numeric entered data is directly represented by its data value.
 - When entering setup data, the full string of parameters need not be entered.

14.2 **COMMANDS**:

SUE{// SUR	= Main Pressure setup.
FLE() / FLR	= Filter setup.
P1E{}/P1R	= Port 1 serial setup.

P2E{} / P2R INE{} / INR TME{} / TMR DTE{} / DTR TIE{} / TIR PAE{} / PAR	 Port 2 serial setup. Input setup. Time. Date. Time/Date Setup Parallel I/O setup
PAE{} / PAR ANE{} / ANR	= Parallel I/O setup = Analog setup.

14.3 **PRESSURE**:

COMMAND:	SUE{}/SUR
DATA FORMA	Γ: <d s=""> <ze%> <z+%> <azm> <mot> <ze set=""> <min></min></ze></mot></azm></z+%></ze%></d>
LENGTH:	Fixed at 13 characters.
WHERE:	
d/s	= Display per Second update rate fixed at 1 number code
ze%	= Zero Aperature % of FS (Zero %) fixed at 1 number code.
z+%	= Zero Band in % of FS (Zero+/-%) fixed at 1 number code.
azm	= AZM Band in divisions (AZM +/-) fixed at 1 number code.

azm = AZM Band in divisions (AZM +/-) fixed at 1 number code. **mot** = Motion Band in divisions (Motion) fixed at 1 number code. **ze set** = Auto Tare or Fixed Offset Zero Set) fixed at 1 number code.

= Minimum Mode enable (Min) fixed at 1 number code. min

Note: The following parameters are not included:

- = Max Mode enable (Max) fixed at 1 number code max
- = Freeze mode select. frez

		CODE #	/PARA	METER A	SSIGN	MENT		Π
CODE #	DSP/ SEC	ZERO %	ZERO +/-%	AZM+/-	MOT ION	ZERO Set	MIN	
0	AUT O	OFF	FULL	OFF	OFF	OFF	OFF	
1	2	0.5	0.05	0.5	1	Auto Tare	ON	
2	3	1	0.1	1	3	OffSet		
3	5	2	0.2	3	5			
4		5	0.5	5	10			
5		100	1	10	20			
6			1.5		50			

14.4 FILTER SETUP:

COMMAND:
DATA FORMAT:
LENGTH:
WHERE:
code

FLE/FLR <code> Fixed at 2 characters.

= Two (2) digit Filter code # from 00 to 20 per table below.

	CODE # / FILTER PARAMETER ASSIGNMENT (FILTR1)									
CODE#	CODE# FILTR 1									
00	1	05	6	10	12	15	25	20	50	
01	2	06	7	11	14	16	30			

02	3	07	8	12	16	17	35	
03	4	08	9	13	18	18	40	
04	5	09	10	14	20	19	45	

EXAMPLE: A filter setting of 14 would be *FLE{11}<cr>

14.5 **PORT 1 SERIAL SETUP**: Not supported at this time.

14.6 **PORT 2 SERIAL SETUP**:

COMMAND:	P2E/P2R
DATA FORMAT:	<mode> <t&d> <data> <eol> <sot> <eot></eot></sot></eol></data></t&d></mode>
LENGTH:	Fixed at 15 characters.
WHERE:	(all codes fixed at one (1) number code; see code tables below)
mode	= Format mode select.
del	= Delay select.
t&d	= Time and Date.
data	= Data select.
eol	= End of line terminator.
sol	= Start of text character.
eot	= End of text character.

	CODE # PORT 2 PARAMETER ASSIGNMENT								
CODE#	MODE DELAY T & D DATA EOL SOT								
0	STD	AUTO	OFF	DISP	CR/LF	STX	NONE		
1	MOD	1 SEC	ON	GTN	CR	NONE	EOT		
2	CUST	2 SEC	ABOVE			SOH	ETX		
3		3 SEC	BELOW				FF		
4		4 SEC					LF		
5		5 SEC							

14.7 INPUT SETUP:

COMMAND:	INE/INR
DATA FORMAT:	< 1> < 2>
LENGTH:	Fixed at 3 characters.
WHERE:	(all codes fixed at one (1) number code; see code table below)
I1	= Input #1
12	= Input #2

CODE # INPUT 1 and 2 PARAMETER ASSIGNMENT			
CODE#	MODE		
0	OFF		
1	Freeze		
2	Zero		
3	Tare		
4	Print		

14.8 TIME/DATE SETUP:

DA ⁻ LEN	MMAND: TA FORMA NGTH: IERE: t1 t2 t3	Fixed (all co = 12 f = Date	/TIR > <t2> <t3> ed at 5 characters. codes fixed at one (1) number code; see code table below) 2 hour or 24 hour select. Pate format select. Pate number or letter select</t3></t2>			
	TIME/DATE PARAMETER ASSIGNMENT					
	CODE#	T1	T2	Т3		
	0	24 HR	MM/DD/YY	NUMBER		

14.9 PARALLEL SETUP:

12 HR

1

	•••
COMMAND:	PAE/PAR
DATA FORMAT:	<par></par>
LENGTH:	Fixed at 1 character.
WHERE:	par: code fixed at one (1) number code; see code table below

DD/MM/YY

LETTER

CODE # PARALLEL PARAMETER ASSIGNMENT				
CODE#	MODE			
0	Parallel OFF			
1	Parallel ON			

14.10 ANALOG SETUP:

COMMAND: DATA FORMAT: LENGTH: WHERE:	ANE{}/ANR <anlg 1=""> <anlg 2=""> <anlg 3=""> <zero> <fs> <zr adj=""> <sp adj=""> Fixed at characters.</sp></zr></fs></zero></anlg></anlg></anlg>
anlg 1 anlg 2 anlg 3 zero fs zr adj sp adj	 = Analog Option select. = 10 or 5 volt output = Select type of data for the analog output. = Zero offset entry. = Full scale entry. = Zero adjust entry. = Span adjust entry.

CODE # / PARAMETER ASSIGNMENT								
CODE#	anlg 1	anlg 2	angl 3	Zero	fs	zr adj	sp adj	
0	ANLG OFF	10 volts	PRESSURE	XXXXXXX X	XXXXXXX X	XXXXXXXX	XXXXXXX X	
1	ANLG ON	5 volts	DELTA T					

14.11 SETPOINT (TRIP POINT) SETUP:

	(
COMMAND:	TNE{}/TNR
DATA FORMAT:	<trip> <disp> <recall> <trip1> <type1> <tp1> <tp1h> <tp1l> <h1h> </h1h></tp1l></tp1h></tp1></type1></trip1></recall></disp></trip>
	<hy1h> <h1l> <hy1l> <trip2> <type2> <tp2> <tp2h> <tp2l> <h2h> </h2h></tp2l></tp2h></tp2></type2></trip2></hy1l></h1l></hy1h>
	<hy2h> <h2l> <hy2l></hy2l></h2l></hy2h>
LENGTH:	Fixed at characters.
WHERE:	

trip disp recall	= Dis	tpoint (Trip Point) Option select. play indication p point status.
<u>TRIP 1</u>	<u>TRIP 2</u>	
trip1	trip2	= Trip point enable
type1	type2	= Trip point type
tp1	tp2	= Trip point polarity
tp1H	tp2H	= Trip point high value of eight (8) digits with leading zeros and no decimal point.
tp1L	tp2L	= Trip point low value of eight (8) digits with leading zeros and no decimal point.
h1H	h2H	= Trip point high hysteresis polarity
hy1H	hy2H	= Trip point high hysteresis value of six (6) digits with leading zeros and no decimal point.
h1L	h2L	= Trip point low hysteresis polarity
hy1L	hy2L	= Trip point low hysteresis value of six (6) digits with leading zeros and no decimal point.

	CODE # / PARAMETER ASSIGNMENT 1 0f 2								
COD E#	trip	disp	recall	trip1 & trip2	type1 & type2	tp1 & tp2			
0	OFF	TRIP	NONE	OFF	TRIP PT	UNDER			
1	ON	ACCEPT	VIEW	ON	BAND	OVER			
2			MODIFY						

CODE # / PARAMETER ASSIGNMENT 2 0f 2							
COD E#	tp1H & tp2H	tp1L & tp2L	h1H & h2H	hy1H & hy2H	h1L & h2L	hy1L & hy2L	
0	XXXXXXX X	XXXXXXX X	DESCEND	XXXXXX	DESCEND	XXXXXX	
1			ASCEND		ASCEND		

15.0 TEMPERATURE CALIBRATION:

> COMMANDS:

TPD	= Temperature Cal on.
TXD	= Temperature Cal off.
TRD	= Temperature reset.
TFR	= Temperature reading.
RZD	= Zero Temp Reference acquire.
RSD	= Zpan Temp Reference acquire
HxD	= Zero Temp Hot acquire (x=1,2 or 3).
HxD	= Span Temp Hot acquire (x=X,Y or Z).
CxD	= Zero Temp Cold acquire.
CxD	= Span Temp Cold acquire.
DxE{}/DxR	= Temperature corrections (x=1 or 2).
TxR	= Temperature diagnostic data recall (x=1,2 or 3).

> TEMPERATURE READING RECALL:

COMMAND:	TFR
DATA FORMAT:	<t data=""></t>
LENGTH:	Fixed at 8 characters
WHERE:	<t data=""> = eight (8) character data field (temp data not in calibrated standard units).</t>

> TEMPERATURE CORRECTIONS DATA ENTRY AND RECALL:

	COMMANDS:	D1E{/D1R and D2E{/D2R
	DATA FORMAT (1):	<zr> <zl1> <zl2> <zl3> <zh1> <zh2> <zh3> <sr> <sl1> <sl2> <sl3> </sl3></sl2></sl1></sr></zh3></zh2></zh1></zl3></zl2></zl1></zr>
		<sh1> <sh2> <sh3></sh3></sh2></sh1>
	DATA FORMAT (2):	<tl1> <tl2> <tl3> <th1> <th2> <th3> <fzl1> <fzl2> <fzl3> <fsl1> </fsl1></fzl3></fzl2></fzl1></th3></th2></th1></tl3></tl2></tl1>
		<fsl2> <fsl3> <fzh1> <fzh2> <fzh3> <fsh1> <fsh2> <fsh3></fsh3></fsh2></fsh1></fzh3></fzh2></fzh1></fsl3></fsl2>
	DATA LENGTHS:	Part (1)=Fixed at 126 characters
	Di tint Eento mio.	Part (2)=Fixed at 171 characters
	WHERE (all paramote	ers eight (8) characters in length):
	Zľ -14/0/0	
	zl1/2/3	Zero low temperature a/d readings.
	zh1/2/3	 Zero high temperature a/d readings.
	sr	= Span Reference
	sl1/2/3	 Span low temperature a/d readings.
	sh1/2/3	 Span high temperature a/d readings
	tr	 Reference temperature
	tl1/2/3	 Low cal temperatures.
	th1/2/3	 High cal temperatures.
	fzl1/2/3	= Zero functions at low temperatures.
	fsl1/2/3	= Span functons at low temperatures.
	fzh1/2/3	= Zero functions at high temperatures.
	fsh1/2/3	 Span functions at high temperatures.
	1311/2/3	- Opan fanctions at hight temperatures.
\triangleright	TEMPERATURE DIAGNO	
	COMMANDS: T1R,	
	DATA FORMAT (1).	<zc> <sc> <wa> <ftl> <ftl2> <ftl3> <fth> <fth2> <fth3> <zr> <zl1> </zl1></zr></fth3></fth2></fth></ftl3></ftl2></ftl></wa></sc></zc>
		<zl2> <zl3> <zh1> <zh2> <zh3></zh3></zh2></zh1></zl3></zl2>
	DATA FORMAT (2):	<sr> <sl1> <sl2> <sl3> <sh1> <sh2> <sh3> <tl1> <tl2> <tl3> </tl3></tl2></tl1></sh3></sh2></sh1></sl3></sl2></sl1></sr>
		<th1> <th2> <th3></th3></th2></th1>
	DATA FORMAT (3):	<fzl1> <fzl2> <fzl3> <fsl1> <fsl2> <fsl3> <fzh1> <fzh2> <fzh3> </fzh3></fzh2></fzh1></fsl3></fsl2></fsl1></fzl3></fzl2></fzl1>
		<fsh1> <fsh2> <fsh3></fsh3></fsh2></fsh1>
	LENGTH: Part (1)= Fixed at 143 characters
	Part (2	2)= Fixed at 125 characters
) = Fixed at 107 characters
		ers eight (8) characters in length):
	zr	= Zero Reference
	zl1/2/3	 Zero low temperature a/d readings.
	zh1/2/3	= Zero high temperature a/d readings.
	sr	= Span Reference
	sl1/2/3	 Span low temperature a/d readings.
	sh1/2/3	
		 Span high temperature a/d readings
	tr	= Reference temperature
	tl1/2/3	= Low cal temperatures.
	th1/2/3	= High cal temperatures.
	fzl1/2/3	 Zero functions at low temperatures.
	fsl1/2/3	 Span functons at low temperatures.
	fzh1/2/3	 Zero functions at high temperatures.
	fsh1/2/3	= Span functions at hight temperatures.
16.0	COMMAND CODE AL	PHABETICAL (xxD=COMMAND, xxR=RECALL & XxE=ENTRY):
	AxE / A	
	CPE /	
	CxD	= Zero Temp Cold acquire (x=1,2 or 3).
	CxD	= Span Temp Cold acquire $(x=X,Y \text{ or }Z)$.

DTE / DTR DxE / DxR FLE / FLR HCD HFE/HFR HNE/HNR HxD HxD INE / INR ISR LCE / LCR LFE / LFR LXE	 = Date. = Temperature Corrections entry and = Filter setup. = Perform Hysteresis cal. = Hysteresis correction. = RPM/HP setup data. = Span Temp Hot Acquire.(x=X,Y or Z = Zero Temp Hot Acquire (x=1,2 or 3) = Input setup. = Input status. = Span Cal Linear corr. All C's. = Span Cal Linear corr. All S's. = Perform Linear Cal at point x; Where 	<u>Z</u>).	
LXE / LXR	= Span Cal Linear corr. All X's.		
MGD	= Display to pressure mode.		;later
MMD	= Display to min mode.	;later	
MND	= Display to net mode.	;later	latar
MPD MSR	 = Display to max mode. = Unit/mode status 		;later
OSR	= Output status.		
PAE/PAR	= Parallel I/O setup.		
PDR	= Display data.		
PGR	= Pressure data.		
PHR	= HP data		
PMR	= Min data.		
PNR	= Applied tare.		;later
PPR	= Max data.		
PRD	= Print to printer port 2.		
PSR	= Pressure status (motion, etc).		
P2E / P2R	·		
REE / RER			
RSD	= Span temp reference acquire.		
RxD	= Linearization Reset ($x = 1-9$ or A)		
RZD	= Zero temp reference acquire.		
SUE/SUR	= Main Pressure setup.		Jatan
	= Tare. / is function of motion etc.		:later
	= Temperature reading.		
	e and Date setup. = Time.		
TME / TMR TNE / TNR	-		
TPD	= Setpoint (Trip Point) setup = Temperature cal on.		
TRD	= Temperature reset.		
TXD	= Temperature cal off.		
TxR	= Temperature disgnostic recall (x=1,2	2 or 3)	
UUE/UUR	= Base 'cal' units config	_ 0. 0)	
UxD	= Select units		
ZCD	= Perform Zero Cal.		
ZED	= Zero.		
ZFE / ZFR	= Zero cal correction.		